

A parallel unstructured implicit 3D polythermal model for outlet glaciers

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IGS 2012-06-28

Outline

Conservative models

Conforming boundaries and model non-smoothness

Multilevel Solvers

Bathymetry and stickyness distribution

- ▶ Bathymetry:
 - ▶ Aspect ratio $\varepsilon = [H]/[x] \ll 1$
 - ▶ Need surface *and* bed slopes to be small
- ▶ Stickyness distribution:
 - ▶ Limiting cases of plug flow versus vertical shear
 - ▶ Stress ratio: $\lambda = [\tau_{xz}]/[\tau_{\text{membrane}}]$
 - ▶ Discontinuous: frozen to slippery transition at ice stream margins
- ▶ Standard approach in glaciology:
Taylor expand in ε and sometimes λ , drop higher order terms.
 - $\lambda \gg 1$ Shallow Ice Approximation (SIA), no horizontal coupling
 - $\lambda \ll 1$ Shallow Shelf Approximation (SSA), 2D elliptic solve in map-plane
 - ▶ Hydrostatic and various hybrids, 2D or 3D elliptic solves
- ▶ **Bed slope is discontinuous and of order 1.**
 - ▶ Taylor expansions no longer valid
 - ▶ Numerics require high resolution, subgrid parametrization, short time steps
 - ▶ Still get low quality results in the regions of most interest.
- ▶ **Basal sliding parameters are discontinuous.**

DB: vht-jako-he5q2-k2em14.dhm

Contour
Var: TemperaturePotential

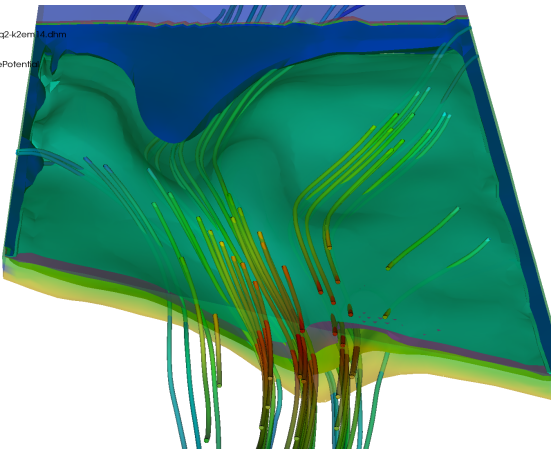


Max: 7.3
Min: -28.

Streamline
Var: Speed



Max: 1.1e+03
Min: 1.5



Polythermal ice

- ▶ Interface tracking methods (e.g. Greve's SICOPOLIS)
 - ▶ Different fields for temperate and cold ice.
 - ▶ Lagrangian or Eulerian, problems with changing topology
 - ▶ No discrete conservation
- ▶ Interface capturing
 - ▶ Enthalpy: Aschwanden, Bueler, Khroulev, Blatter (J. Glac. 2012/PISM)
 - ▶ Not in conservation form
 - ▶ Only conservative for infinitesimal melt fraction
 - ▶ Energy
 - ▶ Conserves mass, momentum, and energy for arbitrary melt fraction
 - ▶ Implicit equation of state

Conservative (non-Boussinesq) two-phase ice flow

Find momentum density ρu , pressure p , and total energy density E :

$$(\rho u)_t + \nabla \cdot (\rho u \otimes u - \eta Du_i + p1) - \rho g = 0$$

$$\rho_t + \nabla \cdot \rho u = 0$$

$$E_t + \nabla \cdot ((E + p)u - k_T \nabla T - k_\omega \nabla \omega) - \eta Du_i : Du_i - \rho u \cdot g = 0$$

- ▶ Solve for density ρ , ice velocity u_i , temperature T , and melt fraction ω using constitutive relations.
 - ▶ Simplified constitutive relations can be solved explicitly.
 - ▶ Temperature, moisture, and strain-rate dependent rheology η .
 - ▶ High order FEM, typically Q_3 momentum & energy
- ▶ DAEs solved implicitly after semidiscretizing in space.
- ▶ Preconditioning using nested fieldsplit
- ▶ Thermomechanical steady state in about 10 nonlinear iterations

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Why care about conforming and non-smoothness?

- ▶ Subshelf ocean circulation is physically richer and more difficult to solve than ice flow
 - ▶ Heat transfer is sensitive to boundary layer processes with thickness < 1 m, $Re \sim 10^6$
 - ▶ Countless engineering studies: wall modeling is limited, significant normal resolution still necessary
 - ▶ Unaligned interface anisotropy is bad for Eulerian AMR methods
- ▶ We care about high-dimensional sensitivity analysis and inversion
 - ▶ Forward model evaluations alone are an inefficient way to explore a high-dimensional space
 - ▶ Each source of model non-smoothness requires a lot of analysis to use adjoint methods
 - ▶ Conforming moving mesh methods eliminate all but “essential” non-smoothness (like contact)

Mesh motion via Inverse Beltrami formulation

- ▶ nonlinear elliptic (or parabolic) equation for mesh location
- ▶ prescribe resolution and anisotropy using target metric tensor
- ▶ efficient solution using Newton-Krylov multigrid or nonlinear multigrid
- ▶ conservative slip boundary conditions at most surfaces
- ▶ ALE transport scheme corrected to satisfy geometric conservation law

Transport

Theorem (Godunov 1954)

Non-oscillatory linear spatial discretizations for transport are at most first order accurate.

- ▶ First order accurate discretizations have unacceptably high numerical diffusion
- ▶ Discretization choices:
 - ▶ Limited or reconstructed finite volume or finite difference
 - ▶ Second order TVD limiters have corners
 - ▶ Weighted Essential Non-Oscillatory (WENO) smooth, but very nonlinear
 - ▶ Central or upwind
 - ▶ Inconvenient for unstructured grids
 - ▶ Nonlinearly stabilized continuous finite element
 - ▶ Currently used, but fragile and messy
 - ▶ Discontinuous Galerkin
 - ▶ Cell-wise entropy stability without limiters
 - ▶ Improved robustness with smooth limiters
 - ▶ Transitioning to this

Joke

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Why do we need multilevel solvers?

- ▶ Elliptic problems are globally coupled
- ▶ Without a coarse level, number of iterations proportional to inverse mesh size
- ▶ High-volume local communication is an inefficient way to communicate long-range information, bad for parallel models
- ▶ Most important with 3D flow features and/or slippery beds
- ▶ Nested/split multilevel methods
 - ▶ Decompose problem into simpler sub-problems, use multilevel methods on each
 - ▶ Good reuse of existing software
 - ▶ More synchronization due to nesting, more suitable after linearization
- ▶ Monolithic/coupled multilevel methods
 - ▶ Better convergence and lower synchronization, but harder to get right
 - ▶ Internal nonlinearities resolved locally
 - ▶ More discretization-specific, less software reuse

Relative effect of the blocks

$$J = \begin{pmatrix} J_{uu} & J_{up} & J_{uE} \\ J_{pu} & 0 & 0 \\ J_{Eu} & J_{Ep} & J_{EE} \end{pmatrix}.$$

- J_{uu} Viscous/momentum terms, nearly symmetric, variable coefficients, anisotropy from Newton.
- J_{up} Weak pressure gradient, viscosity dependence on pressure (small), gravitational contribution (pressure-induced density variation). Large, nearly balanced by gravitational forcing.
- J_{uE} Viscous dependence on energy, very nonlinear, not very large.
- J_{pu} Divergence (mass conservation), nearly equal to J_{up}^T .
- J_{Eu} Sensitivity of energy on momentum, mostly advective transport. Large in boundary layers with large thermal/moisture gradients.
- J_{Ep} Thermal/moisture diffusion due to pressure-melting, $u \cdot \nabla$.
- J_{EE} Advection-diffusion for energy, very nonlinear at small regularization. Advection-dominated except in boundary layers and stagnant ice, often balanced in vertical.

How much nesting?

$$P_1 = \begin{pmatrix} J_{uu} & J_{up} & J_{uE} \\ 0 & B_{pp} & 0 \\ 0 & 0 & J_{EE} \end{pmatrix}$$

- ▶ B_{pp} is a mass matrix in the pressure space weighted by inverse of kinematic viscosity.
- ▶ Elman, Mihajlović, Wathen, JCP 2011 for non-dimensional isoviscous Boussinesq.
- ▶ Works well for non-dimensional problems on the cube, not for realistic parameters.
 - ▶ Low-order preconditioning full-accuracy unassembled high order operator.
 - ▶ Build these on command line with PETSc PCFieldSplit.

$$P = \begin{bmatrix} \begin{pmatrix} J_{uu} & J_{up} \\ J_{pu} & 0 \end{pmatrix} & \\ \begin{pmatrix} J_{Eu} & J_{Ep} \end{pmatrix} & J_{EE} \end{bmatrix}$$

- ▶ Inexact inner solve using upper-triangular with B_{pp} for Schur.
- ▶ Another level of nesting.
- ▶ GCR tolerant of inexact inner solves.
- ▶ Outer converges in 1 or 2 iterations.

Full Approximation Scheme

$$\begin{aligned} \tilde{u}^h &\leftarrow S_{\text{pre}}^h u_0^h && \text{pre-smooth} \\ L^H u^H &= I_h^H f^h + \underbrace{L^H \hat{I}_h^H \tilde{u}^h - I_h^H L^h \tilde{u}^h}_{\tau_h^H} && \text{solve coarse problem for } u^H \\ u^h &\leftarrow S_{\text{post}}^h \left[\tilde{u}^h + I_H^h (u^H - \hat{I}_h^H \tilde{u}^h) \right] && \text{apply correction and post-smooth} \end{aligned}$$

- ▶ Nonlinearities from spatial discretization fixed locally
- ▶ No assembled matrices so better floating point utilization, less memory
- ▶ Makes progress on all physical components at once
- ▶ FD and DG good, less efficient for continuous finite element methods
- ▶ Influence of surface evolution is low rank, no need to visit finest level on each iteration

Outlook

- ▶ Basal hydrology model
 - ▶ Need mesh-independent statistics
 - ▶ Numerical homogenization?
- ▶ True inverse and sensitivity support, but need to invert for the right thing
- ▶ Dynamic remeshing after large topology changes
- ▶ Finish FAS multigrid for full coupled system including geometry
- ▶ User-friendliness of process
 - ▶ Currently using georeferenced initial/boundary data via GDAL
 - ▶ But meshing process is not fully automatic
 - ▶ Better: multiresolution database (Mark Fahnstock)